

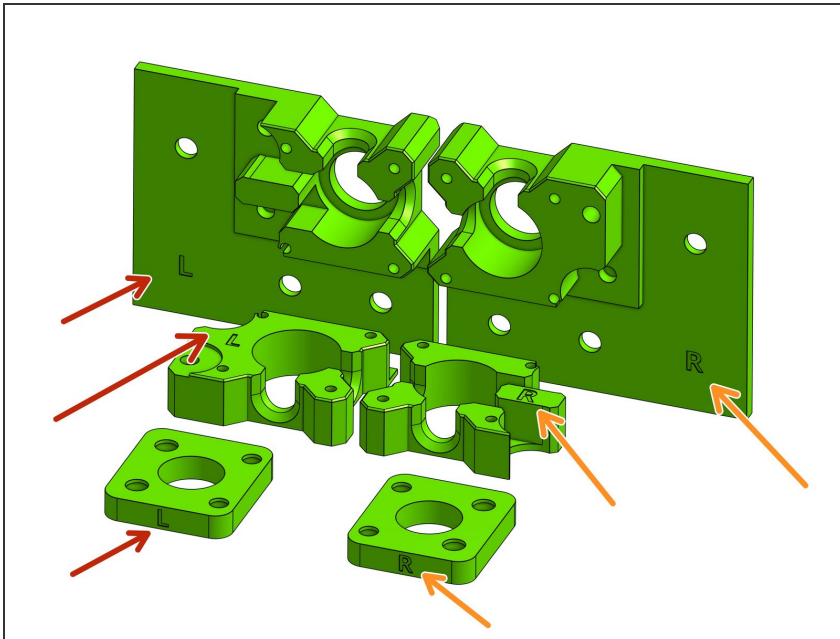
Rat Rig

02. XY Drive Assembly

Written By: Paweł Kucmus



Step 1 — Identify the printed parts

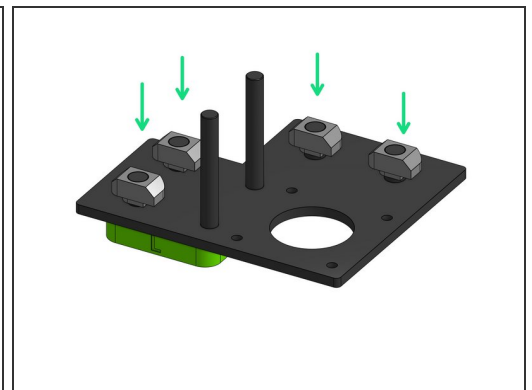
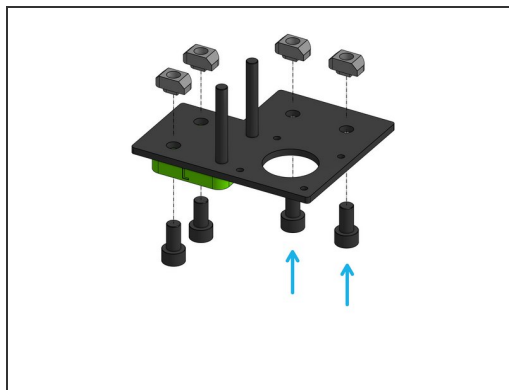
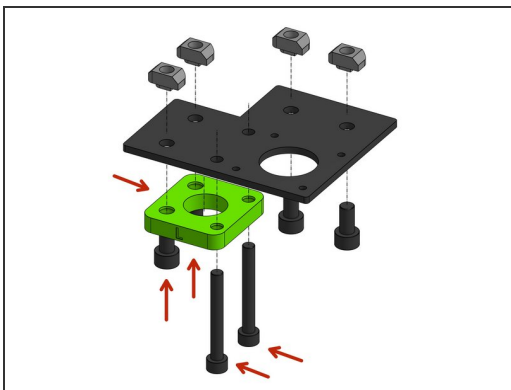


- Fetch these six parts and look for letters indicating which parts belong to which side:

- The letter **L** for left
- The letter **R** for right

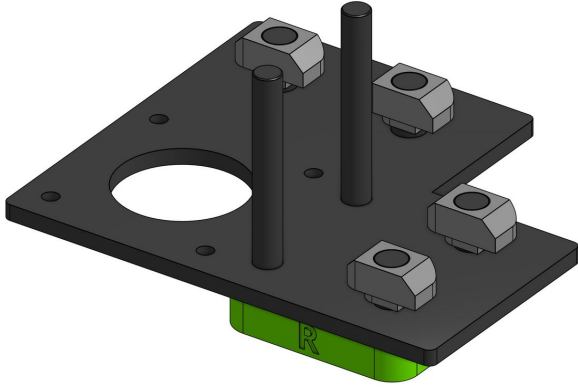
⚠ The sides do not differ much, but the parts are **NOT** mirrored

Step 2 — Prepare the left drive base



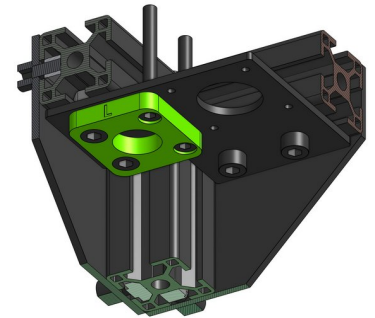
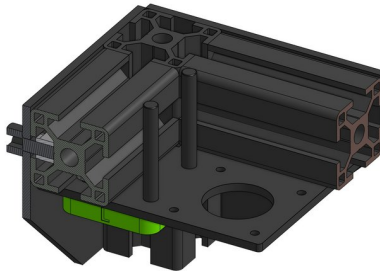
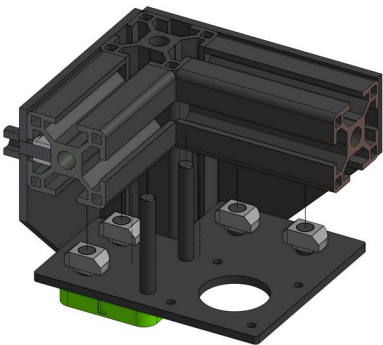
- Thread the two **Cap Head Screw M5x40** and two **Cap Head Screw M6x12** screws through the **motor_support_l** part
- The **motor_support_l** part is supposed to hold the screw heads tightly
- Thread the support assembly through the **motor_plate** along with the remaining two **Cap Head Screw M6x12** screws
- Attach the **3030 M6 T-nuts**. Don't tighten fully yet.

Step 3 — Prepare the right drive base



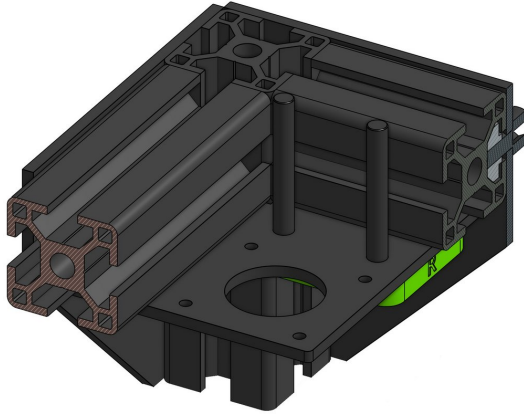
- Repeat the previous step for the right side with the use of **motor_support_r** part

Step 4 — Attach the left drive base



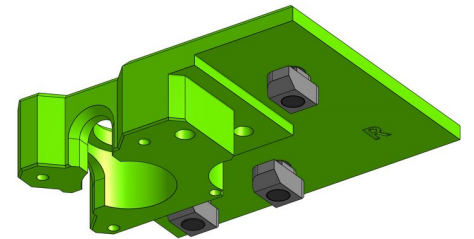
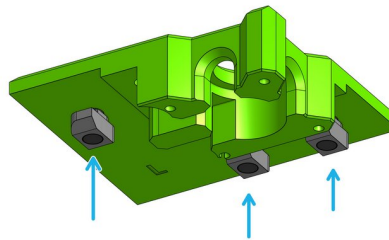
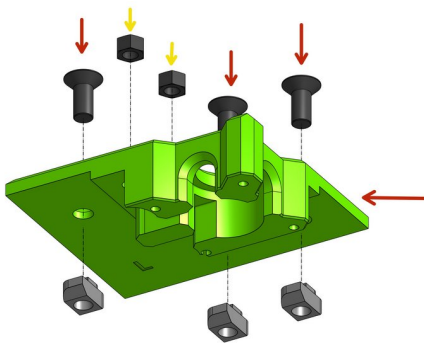
- Attach the left drive base to the left top corner of the printer
- Make sure the plate is in the corner and tighten the **M6 screws** to lock the **T-Nuts** in place
- ⓘ The T-Nuts need to rotate within the 3030 extrusion for a secure attachment

Step 5 — Attach the right drive base



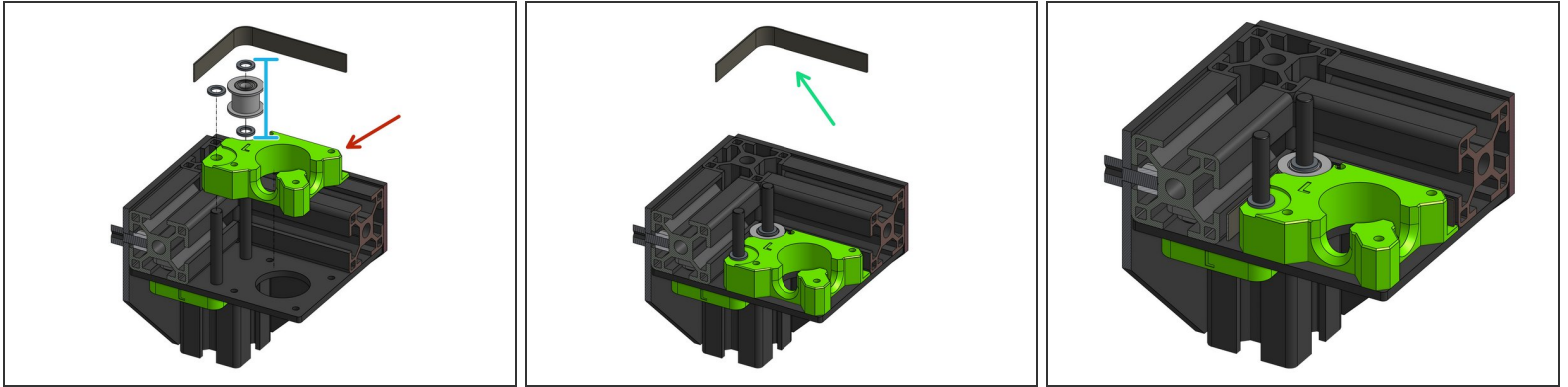
- Repeat the previous step on the right side

Step 6 — Prepare the top parts



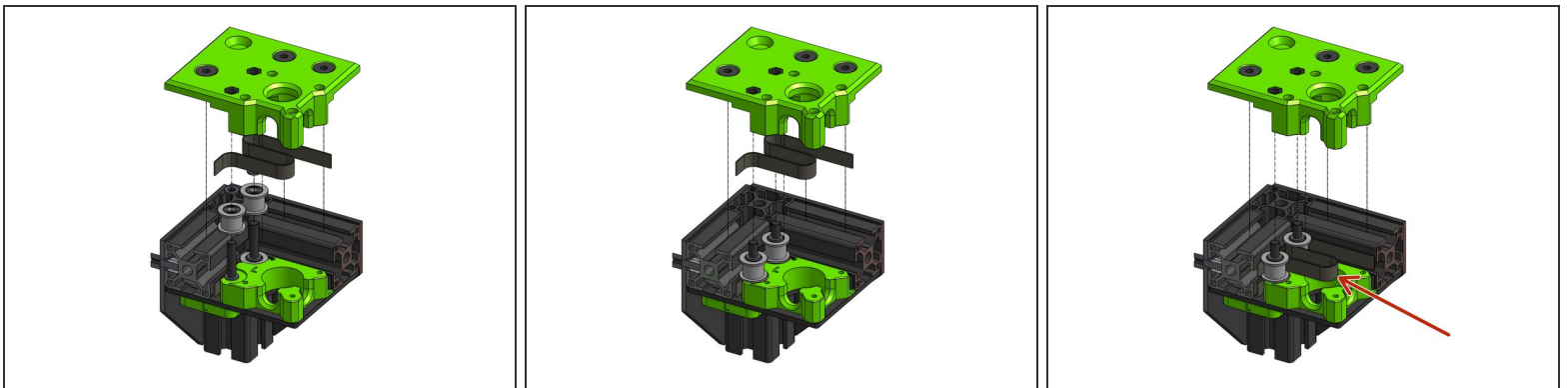
- The three **Countersink Screw M6x14** (the countersunk ones) and thread those through the **xy_motor_cage_top_left** printed part
- Attach the **3030 M6 T-nuts**, don't tighten fully
- Pull the **M5 Hex Locking Nuts** into place with the nut pull technique (described in the [Preparations guide](#))
- Repeat on the **xy_motor_cage_top_right** part

Step 7 — Assemble the bottom of the left motor drive



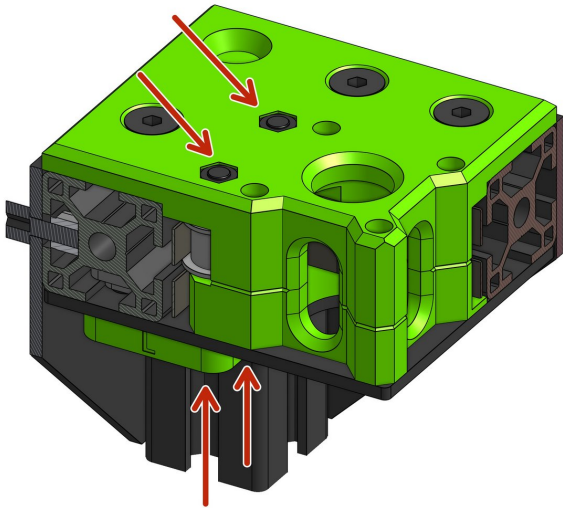
- Slide the **xy_motor_cage_bottom_left** part onto the M5 screws
- Add one **precision shim** on the **M5 screw** going through the printed part and **shim, idler, shim** on the second **M5 screw**
- Put the belt in, flat side on the idler, leave the ends of the belt hanging loose

Step 8 — Assemble the top of the left motor drive



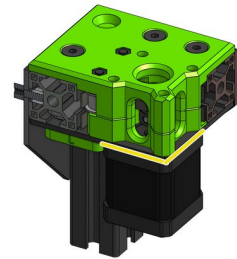
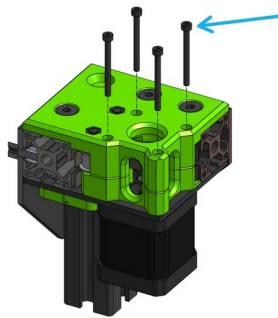
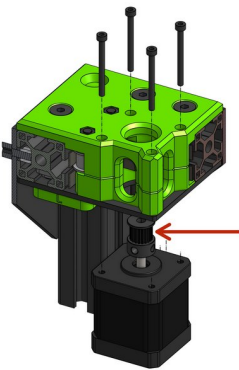
- Side one **smooth idler** on each of the two **M5 screws**, add **shims** on top of them
- Fold the top belt over the idlers, smooth side on the idler
- Leave a large loose loop on the top belt - you will need to thread the motor pulley through it later on

Step 9 — Attach the top part of the left drive



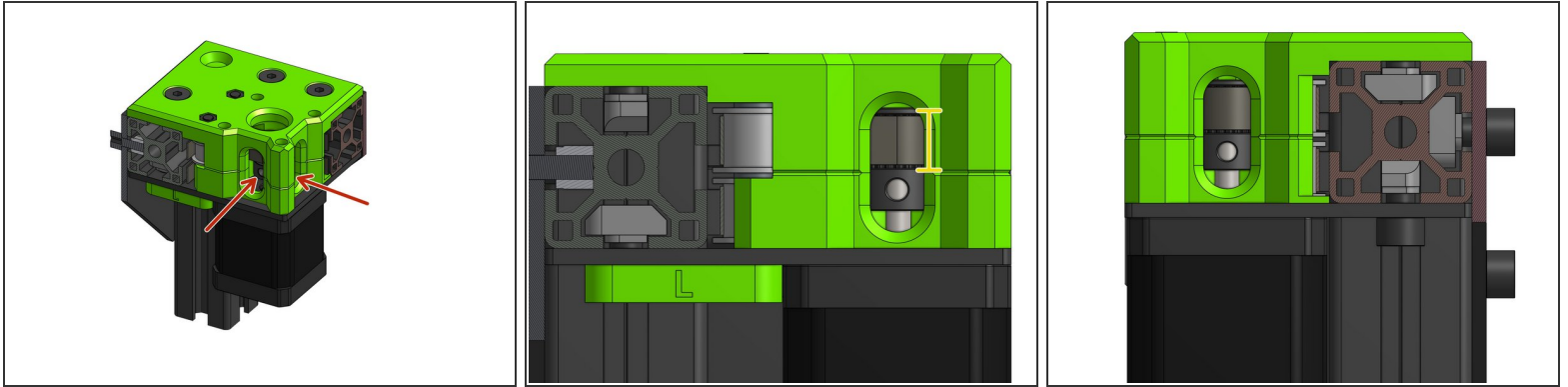
- Place the top part on the assembly and fasten it with the **M5 screws** from underneath. The parts need to be flush but not so tight that they'll stop the idlers from rotating
- ⚠ Do not over tighten or you will be compressing the bearings.
- Fasten the **Countersink Screws** at the top - remember that the T-Nuts inside need to rotate and grab the inside of the 3030 extrusion

Step 10 — Attach the stepper motor



- Put the **motor pulley** on the motor shaft with the teeth oriented up
- Attach the motor to the assembly with four **Cap Head Screws M3x35**. The motor pulley needs to get into the belt loop you left loose on the previous step
- Make sure the motor is sitting flush against the plate

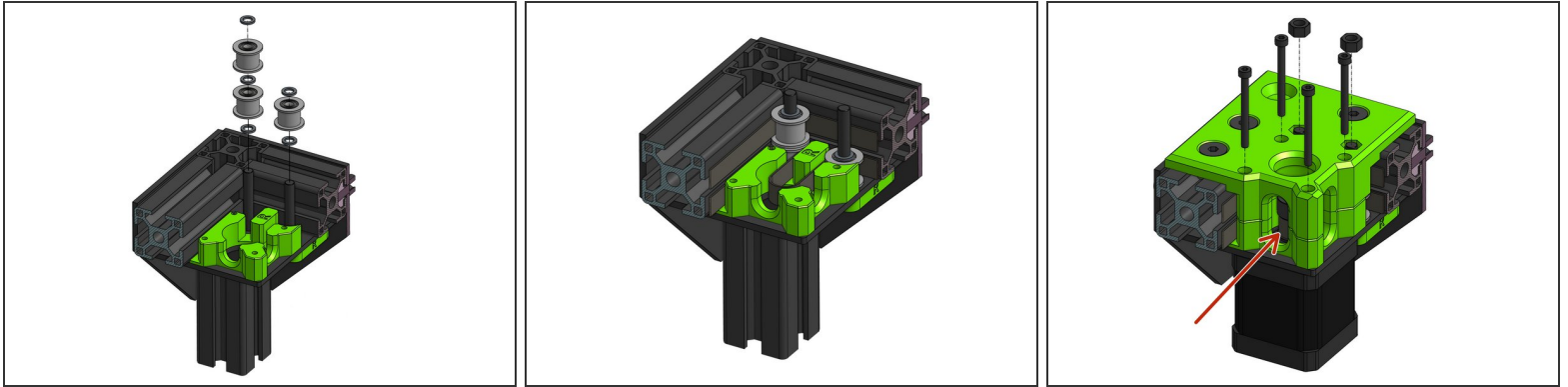
Step 11 — Make sure the pulley is placed correctly



⚠ This is one of the most important steps in the whole manual - failure to align the belts will result in rubbing and belt failure!

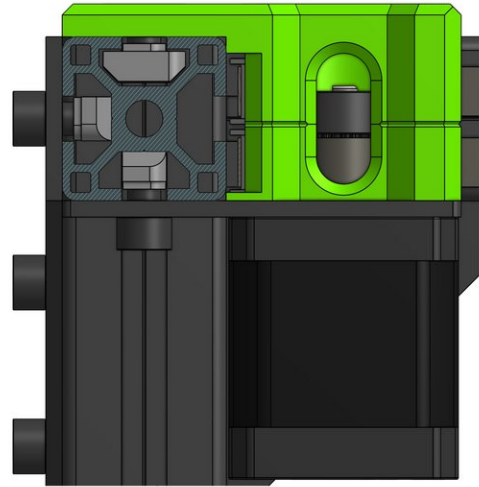
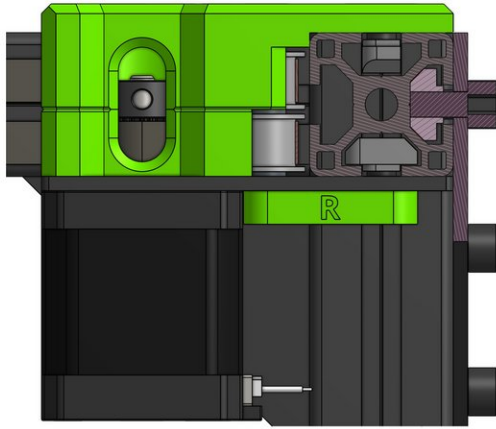
- Tighten the belt to remove the loose belt loop we left in the previous steps. Align the pulley to see both pulley grub screws through the openings in the printed parts
- Make sure the belt is in the middle of the pulley
- Tighten the grub screws on the pulley. **One of the set screws should be in contact with the flat side of the motor shaft**

Step 12 — Assemble the right motor drive



- i** The right motor drive is very similar to the left one with the difference that the bottom belt is driven so there are two idlers at the bottom and one on top
- Attach the motor plate with the **motor_support_r** part and corresponding screws and nuts
 - Place the **xy_cage_bottom** printed part on the motor plate and thread the five **shims** with 3 **smooth idlers** on the M5 screws
 - Attach the top part
- ⚠ Do not over tighten or you will be compressing the bearings.**
- Unlike the in the left drive the pulley on the right drive has it's teeth downwards

Step 13 — Make sure the pulley is placed correctly



⚠ As with the left motor this is a crucial step!

- Ensure the belt pulley is aligned properly with the belt once you pull the belt loop back
- Tighten the pulley motor screws

Step 14 — Next guide...



- [03. XY Idler Assembly](#)